## Basics of measurement and modeling of MEG

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CIBA 130

7. 12. 2015

## • Basics of MEG

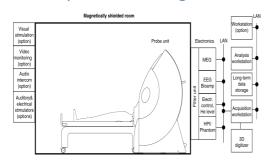
- technology
- origins of the signal
- measurement and noise
- · Data analysis
  - source reconstruction
  - neuronal oscillations
  - connectivity

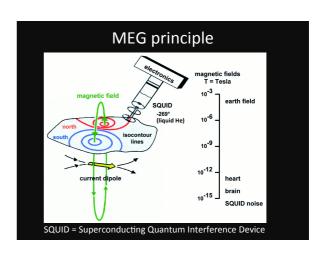


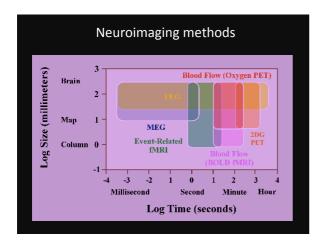
## MEG components

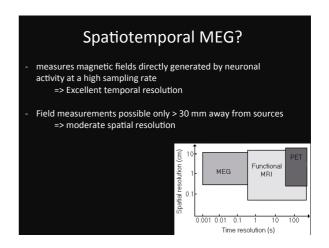
- Magnetometer device
  - sensors
  - electronics
  - software
- Magnetically shielded room
- Electric signal amplifiers
- · Stimulus devices
- Response devices
- Monitoring etc. devices

## System block diagram



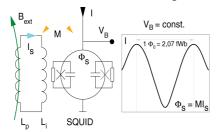




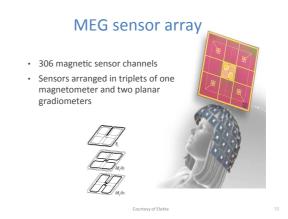


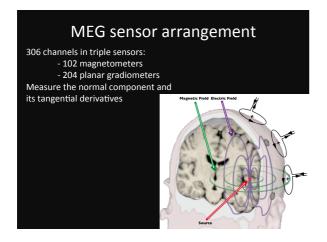
## SQUID readout principle

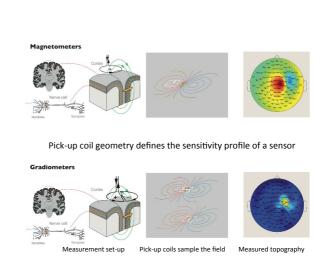
- Superconducting QUantum Intereference Device
- SQUIDs needed to detect this small magnetic fields

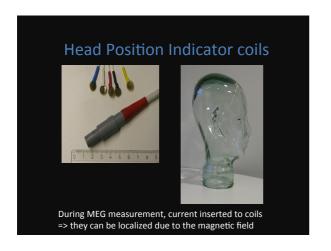


B<sub>ext</sub>: the measured magnetic field











## Trigger interface system

- Synchronization of external events to brain events
- Merged to MEG data stream
- 16 ch I/O



## Noise in MEG signals

- Non-neuronal magnetic signals from the body
  - Heart
  - Retination
  - Muscles (ocular, scalp, neck, jaws, breathing)
  - Magnetized objects
- External noise sources
  - Traffic, electric lines, motors and devices, Earth, ...

## Rejection of noise in MEG signals

Magnetically shielded room:

- layered mu-metal and aluminium
- High permeability
  - => "catches" and aligns magnetic field lines
- Works as Faraday's cage for EEG as well
- Shielding factors of ~106
- from DC to radio frequencies

## Rejection of noise in MEG signals

Signal processing techniques

- spatial and frequency filtering methods
- Maxwell filtering ("SSS" by Elekta)
- Signal decomposition methods (PCA, ICA)

Reference sensors / compensation coils

• Internal active shielding, IAS

## Rejection of noise in MEG signals

It is best to minimize noise in the first place:

- check the environment
- empty-room test measurement
- test measurement with the subject
- monitor signals during data acquisition

## **Concurrent EEG**

- Simultaneous EEG possible
- Non-magnetic electrodes & leads required
- No additional interference from MEG
  - movement artifacts
  - size constraints
  - preparation time
- Also EOG, EKG, EMG, ...

## Other device options at MEG

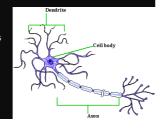
- · Stimulation devices
  - Visual, auditory, somatosensory
- Response devices
  - Finger pads, accelerometers,
- Monitoring devices
  - cameras, microphones, eye-tracking

## Do we see a neuronal signal with MEG?

• Neurophysiology & physics

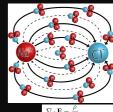
## Neurophysiology

- Neurons
  - · Axon, soma and dendrites
- Synapses
- Electric phenomena
  - Action potentials
  - Post-synaptic potentials



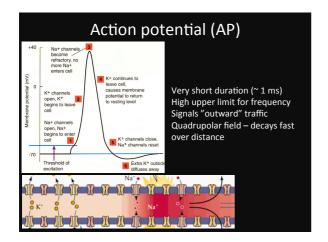
## Neurophysiology

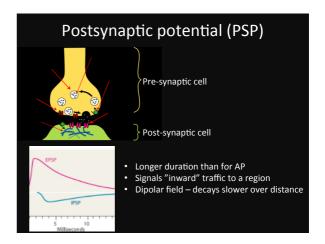
- *lons* are the basis of electric phenomena in biology
  - K+, Na+, Cl-, Ca2+
- Electrically charged =>
  - o Generate an electric field
  - o movement = electric current
     ⇒ Magnetic field
- Physics of magnetic and electric fields known for 150 years
  - o Maxwell's equations



 $\nabla \cdot \mathbf{E} = \frac{\mathbf{r}}{\varepsilon_0}$   $\nabla \cdot \mathbf{B} = 0$   $\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$ 

 $\nabla \times \mathbf{B} = \mu_0 \mathbf{J} + \mu_0 \varepsilon_0 \frac{\partial \mathbf{E}}{\partial t}$ 





## What is needed for a signal?

## What is needed for a signal? • several cells: — Fields linearly additive • same location and direction => cumulation — Activation at the same time (synchronous) — Field geometry that decays slowly with distance • Dipolar rather than higher order fields — Large currents

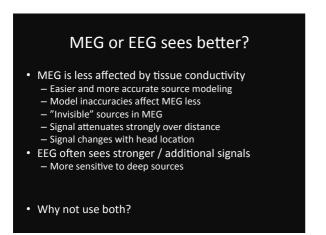
to the field.

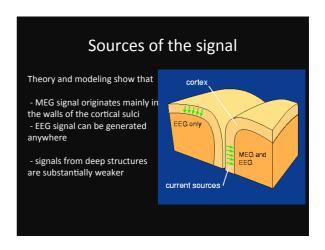
## Cortical gray matter Layer 5 large pyramidal cells are considered important for generation of the MEG signal Roughly speaking, order of 10000s of cells needed for a signal

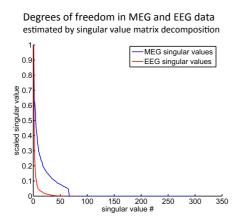
## MEG or EEG sees better? EEG measures the electric potential difference between two electrodes. The potential difference is due to extracellular volume currents flowing in a resistive medium (scalp). Volume currents are induced by intracellular primary currents. MEG measures the magnetic field generated by primary currents outside the head. Secondary volume currents usually contribute

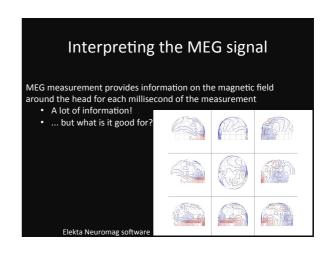
• In EEG we have the *reference* problem; MEG is reference-free

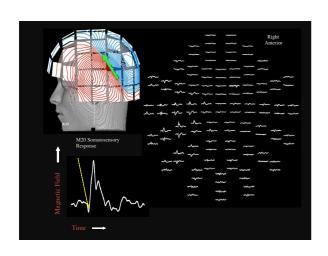
EEG signal depends on the conductivity geometry highly, MEG signal somewhat

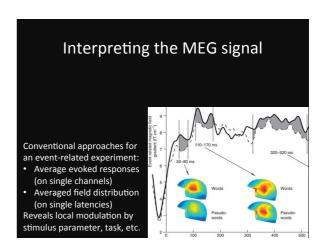












## Source modeling of MEG data

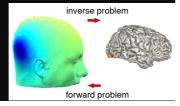
- Channel-level analysis reveals effect timing
- Anatomically specific findings require transforming the channel-space data to source-space data
- Requires knowledge of the system and understanding of electromagnetic field theory

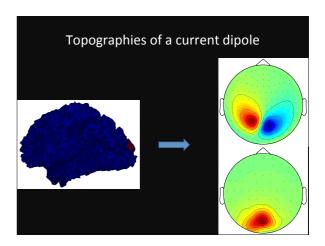
## Source reconstruction, a.k.a. inverse modeling

- Relates the channel information to activity in actual brain regions
- A bunch of different approaches / practices used; even more proposed for use
  - None of these is the correct one!
    - No unique solution exists
- Highly affects the relevance of further analyses!
  - can be dangerous if done wrong

## Forward or inverse problem?

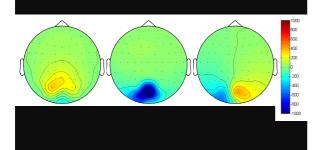
- forward: what kind of field is generated by a given source?
- inverse: what kind of source configuration may generate the measured magnetic field?

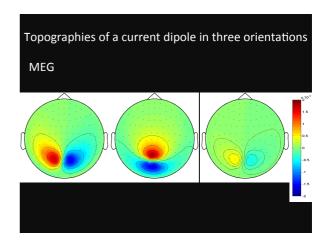


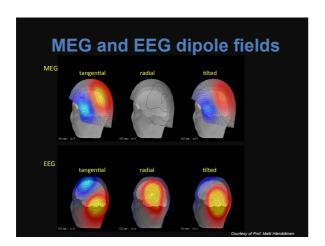


Topographies of a current dipole in three orientations

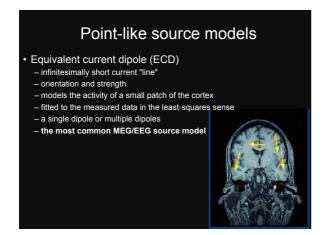
EEG

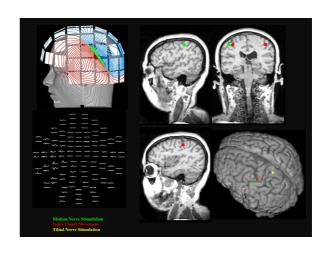




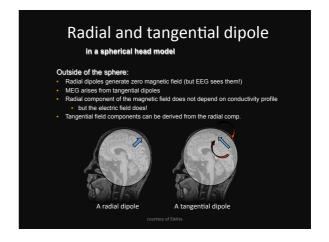


## Methods for inverse modeling • dipole models - specify 1-4 dipoles; fixed, moving, rotating, ... • distributed current solutions - Minimum norm estimates (MNE) - LORETA (low resolution tomography) • beamformers - adaptive estimates for source strength per voxel - not real/complete inverse solutions; properties unknown • signal decomposition methods - explain the data with interpretable components - do not go to source space at all





# Source modeling in a sphere For MEG sphere model, we need: Origin of the sphere Sensor information Theory, e.g. the field of a current dipole

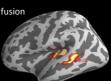


## Source modeling in evoked response studies

Traditionally, (single) dipole modeling has prevailed

Distributed source models estimate source current strength all over the cortex

- Helps interpret the findings
- May work as a sanity check
- A straightforward way to MEG/EEG data fusion

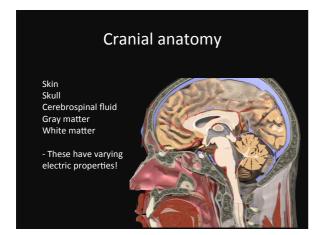


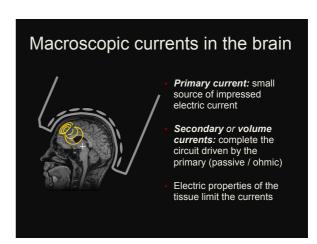
## Source modeling in realistic anatomy

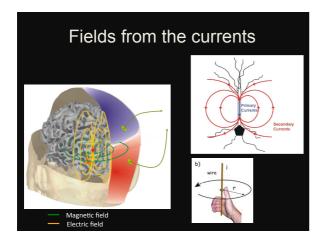
We first need

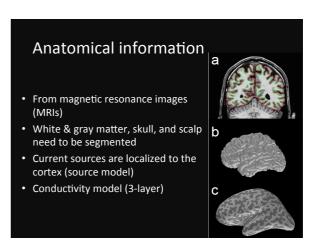
- The anatomy
- Potential signal sources
- Electric model of tissue properties
- Measurement geometry & forward model
- Inverse modeling theory (a priori assumptions)

This will take a while...





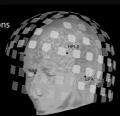


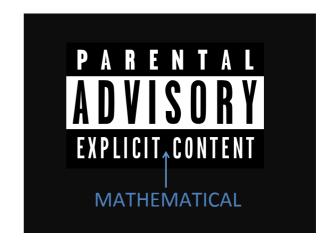


## Forward model

Based on head model, device geometry, and the relationship between these two

- Segmented MRI
- Realistic tissue conductivities
- Cortically constrained source locations
- Field computations using boundary element method (BEM)
- Sensor information
- Head position information (HPI)





## Linear forward and inverse problem

M/EEG problems are linear => matrices

Gx = v

G is the forward model x are the source activations y is the measurement result (when forgetting noise)

We are looking for

$$X = G^{-1}GX = G^{-1}y$$

 $G^{-1}$  or inverse of G is a matrix for which  $G^{-1}G=1$ 

Unluckily, such a matrix does not exist in this case.

### Forward and inverse problem

Typically in MEG: 306 channels
Typical source model: ~6000 sources

• More unknowns than data points => infinite number of "correct" solutions

Which one should we choose?

## The minimum norm estimate

We impose *a priori* information to select only one of the infinite correct solutions

MNE supposes that:

- Source amplitudes are normally distributed with known co-variance
- The measurement includes normally distributed noise with a known co-variance
- (Sources are located in the cortical gray matter)

A priori information could be something else ⇒ different (perhaps equally correct) solution

Problems: difficult to validate sensitive to noise

## Minimum norm estimate

MNE is the solution with the smallest total source energy; in mathematical terms, the minimum  $L^2$ -norm:

 $|x| = \operatorname{sqrt}(x_1^2 + x_2^2 + \dots + x_n^2)$ 

cf. Pythagoras:  $h = \operatorname{sqrt}(a^2 + b^2)$ 



Such solutions are generally found using the pseudoinverse of  $G, G^+$ :

 $x = G^+ y = G^T (GG^T)^{-1} y$ 

We more often use a regularized solution:

MNE:  $x = RG^T(GRG^T + \lambda^2C)^{-1}y$ 

R source covariance (often diagonal => sources *a priori* independent) G gain matrix (forward solution)

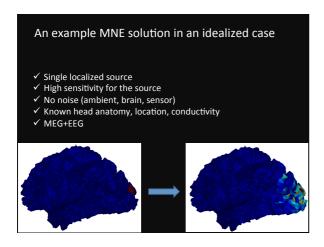
## Noise covariance matrix – statistics of non-interesting signals Is needed for the inverse model Is used to give the noisiest signals the lowest significance Noise covariance matrix for 102 magnetometers from an empty-room MEG measurement

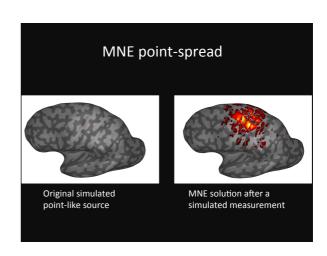
## Unmodeled noise in MEG

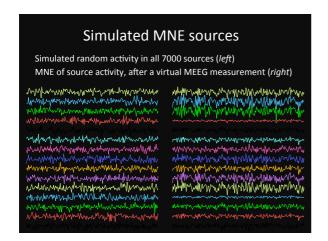
- = sensor noise components not included in noise covariance
- Bioelectric sources of the subject: EKG, EOG. EMG
- Clothing, dental work, jewelry, surgery, ...
- Head movements
- Radio frequency interference
- Stimulator devices
- Transient external noise

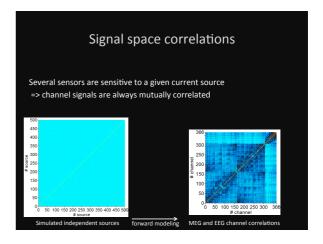
MNE models these as currents in the cortex!

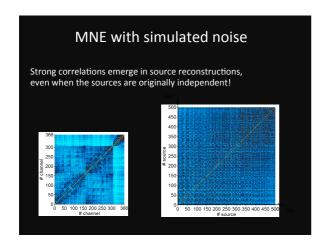
• So clean up your data first

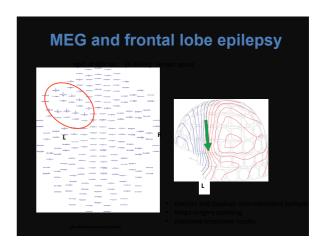


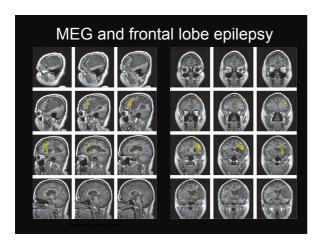












## MEEG data preprocessing Data include several artifacts that might cause unpredictable errors in source localization and affect response size and shape, destroying it all Getting rid of non-neuronal MEEG signal components using ICA: • low-frequency components (blinks, movements, heart) • high-frequency components (saccades, muscles) - several rejection criteria for ICs: • scalp topography • frequency content • time courses wrt. experiment • correlation with EOG/EKG • higher-order statistical properties

