

Let's consider again the model Hamiltonian

$$\hat{H} = \int \left(-\psi^\dagger \frac{\nabla^2}{2m} \psi + \frac{\lambda}{2} \psi^\dagger \psi \psi^\dagger \psi \right) d^3x$$

$$\begin{cases} \psi^M = e^{\hat{H} \tau} \psi e^{-\hat{H} \tau} \\ \bar{\psi}^M = e^{\hat{H} \tau} \bar{\psi} e^{-\hat{H} \tau} \end{cases}$$

Use Eqs. of motion

$$\frac{\partial}{\partial \tau} \psi^M = [H, \psi^M] \quad \frac{\partial}{\partial \tau} \bar{\psi}^M = [H, \bar{\psi}^M]$$

$$\begin{cases} \left(\frac{\partial}{\partial \tau} - \frac{\nabla^2}{2m} \right) \psi + \lambda \bar{\psi} \psi = 0 \\ \left(\frac{\partial}{\partial \tau} + \frac{\nabla^2}{2m} \right) \bar{\psi} - \lambda \bar{\psi} \psi = 0 \end{cases}$$

$$\begin{aligned} -[\psi^\dagger \psi, \psi] &= \psi^\dagger \psi^\dagger \psi - \psi^\dagger \psi \psi \\ &= \delta_{\alpha\beta} \psi \\ -[\psi^\dagger \psi, \psi^\dagger] &= \psi^\dagger \psi^\dagger \psi - \psi^\dagger \psi \psi^\dagger = -\psi^\dagger \delta_{\alpha\beta} \\ &= -\psi^\dagger \delta_{\alpha\beta} \end{aligned}$$

$$G^M = T_4 \left(\rho^T \psi^M(x_1, \tau) \bar{\psi}^M(x_2, 0) \right) = \langle T \psi^M(x_1, \tau) \bar{\psi}^M(x_2, 0) \rangle$$

$$\begin{aligned} \left(\frac{\partial}{\partial \tau} - \frac{\nabla^2}{2m} \right) G^M &= \frac{\partial}{\partial \tau} G^M = \delta(x_1 - x_2) \delta(\tau) + T_4 \left(\rho^T \frac{\partial}{\partial \tau} \psi^M(x_1, \tau) \bar{\psi}^M(x_2, 0) \right) = \\ &= \delta(x_1 - x_2) \delta(\tau) + T_4 \left(\rho^T \left(\frac{\nabla^2}{2m} \psi - \lambda \bar{\psi} \psi \right) \bar{\psi}^M(x_2, 0) \right) = \end{aligned}$$

$$\begin{aligned} \text{Therefore } \left(\frac{\partial}{\partial \tau} - \frac{\nabla^2}{2m} \right) G_{\alpha\beta}(x_1, \tau, x_2, 0) &= \delta(x_1 - x_2) \delta(\tau) \delta_{\alpha\beta} - \lambda T_4 \left(\rho^T (\bar{\psi}^\dagger \psi) (x_1, \tau) \bar{\psi}^M(x_2, 0) \right) \\ &= \delta(x_1 - x_2) \delta(\tau) \delta_{\alpha\beta} - \lambda T_4 \rho^T \left(\bar{\psi}^\dagger \psi \right)_{(x_1, \tau)} \bar{\psi}^M(x_2, 0) \end{aligned}$$

Use the same trick with mean-field approximation

$$\begin{aligned} \langle T (\bar{\psi}^\dagger \psi(x_1) \bar{\psi}^M(x_2)) \rangle &= \langle T \bar{\psi}^\dagger_{(x_1)} \psi_{(x_1)} \bar{\psi}^M(x_2) \rangle = \langle \bar{\psi}^\dagger_{(x_1)} \psi_{(x_1)} \rangle \langle \bar{\psi}^M(x_2) \rangle = \\ &= F^+(x_1, x_2) \Delta(x_2) \end{aligned}$$

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