

Vektorianalyysi
k. 2014

Ex Tempore 7

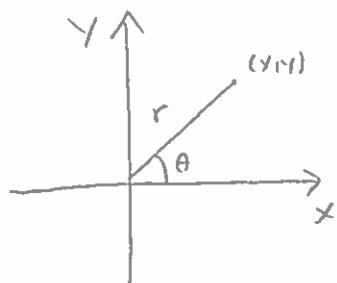
Ma 31.3.

1.

- a) Mitkä ovat pisteen $(x, y) = (1, 1)$ napakoordinaatit (r, θ) ?
 - b) Mitkä ovat sylinterikoordinaatiston pisteen $(\rho, \theta, z) = (\sqrt{2}, \frac{\pi}{4}, 1)$ karteiset koordinaatit (x, y, z) ?
 - c) Mitkä ovat pisteen $(x, y, z) = (1, 1, \sqrt{2})$ pallokoordinaatit (r, ϕ, θ) ?
2. Alue A määritellään seuraavasti: $A = \{x \leq 0, y \geq 0, x^2 + y^2 \leq 1\}$.
- a) Laske alueen A pinta-ala tekemällä muuttujanvaihto napakoordinaatteihin.
 - b) Laske integraali $\iint_A dA (3x^2 + 3y^2)$.
3. Kuinka suuri osa maapallon pinnasta on pohjoisten leveyspiirien 60° ja 70° välisellä alueella?
4. Laske funktion $f = \arctan \frac{y}{x}$ pintaintegraali yli alueen $D = \{0 \leq x \leq 1, 0 \leq y \leq \sqrt{1 - x^2}\}$.

1.

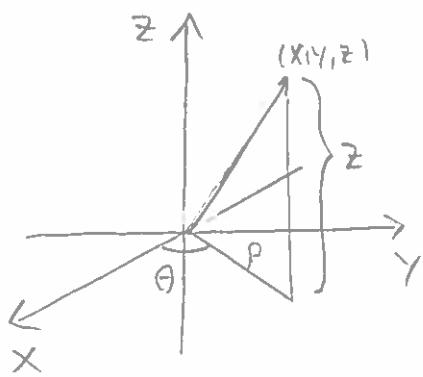
a.) Napakoordinaat-tummuus



$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ r = \sqrt{x^2 + y^2} \\ \theta = \arctan\left(\frac{y}{x}\right) \end{cases}$$

$$(x, y) = (1, 1) \Rightarrow (r, \theta) = (\sqrt{2}, \frac{\pi}{4})$$

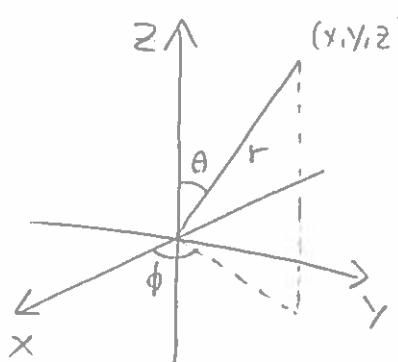
b.) Sylinterikoodinaat-tummuus



$$\begin{cases} x = \rho \cos \theta \\ y = \rho \sin \theta \\ z = z \\ \rho = \sqrt{x^2 + y^2} \\ \theta = \arctan\left(\frac{y}{x}\right) \\ z = z \end{cases}$$

$$(\rho, \theta, z) = (\sqrt{2}, \frac{\pi}{2}, 1) \Rightarrow (x, y, z) = (1, 1, 1)$$

c.) Pallokoordinaat-tummuus



$$\begin{cases} x = r \sin \theta \cos \phi \\ y = r \sin \theta \sin \phi \\ z = r \cos \theta \end{cases}$$

$$(x, y, z) = (1, 1, \sqrt{2}) \Rightarrow (r, \phi, \theta) = (2, \frac{\pi}{4}, \frac{\pi}{4})$$

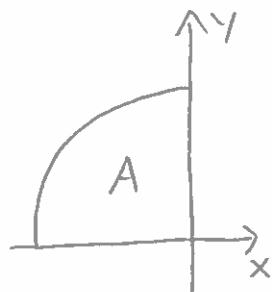
$$\begin{cases} r = \sqrt{x^2 + y^2 + z^2} \\ \phi = \arctan\left(\frac{y}{x}\right) \\ \theta = \arctan\left(\frac{z}{\sqrt{x^2 + y^2}}\right) \end{cases}$$

Huom. Muista tarkistaa arctanin antamat numerot!

[2.] $A = \{x \leq 0, y \geq 0, x^2 + y^2 \leq 1\}$

Piirrä aina ensin kuval

Parametrisoidaan alue A.



$$\begin{aligned} x &= r \cos \theta, \quad r \in [0,1] \\ y &= r \sin \theta, \quad \theta \in [\frac{\pi}{2}, \pi] \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{Napulkoordinatitilumus.}$$

O $\vec{r}(r, \theta) = r \cos \theta \hat{i} + r \sin \theta \hat{j}$

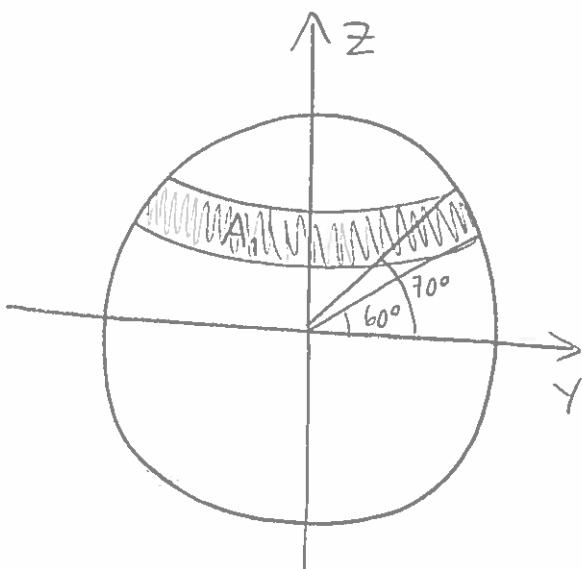
$$\begin{aligned} \frac{\partial \vec{r}}{\partial r} &= \cos \theta \hat{i} + \sin \theta \hat{j} \\ \frac{\partial \vec{r}}{\partial \theta} &= -r \sin \theta \hat{i} + r \cos \theta \hat{j} \end{aligned} \Rightarrow \frac{\partial \vec{r}}{\partial r} \times \frac{\partial \vec{r}}{\partial \theta} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \cos \theta & \sin \theta & 0 \\ -r \sin \theta & r \cos \theta & 0 \end{vmatrix}$$

$$= \hat{k} (r \cos^2 \theta + r \sin^2 \theta) = r \hat{k}$$

a.) $\int_A ds = \int_0^1 dr \int_{\frac{\pi}{2}}^{\pi} d\theta \frac{r}{\sqrt{r^2}} = \frac{\pi}{2} \int_0^1 dr r = \frac{\pi}{4}$
 $= |\vec{J}| = \left| \frac{\partial \vec{r}}{\partial r} \times \frac{\partial \vec{r}}{\partial \theta} \right|$

b.) $\int_A ds (\underbrace{3x^2 + 3y^2}_{3(x^2 + y^2) = 3r^2}) = \int_0^1 dr \int_{\frac{\pi}{2}}^{\pi} d\theta 3r^2 \cdot r = \frac{3\pi}{2} \int_0^1 dr r^3 = \frac{3\pi}{8}$

3.



Lasketaan pohjoisten leveyspiirien 60° ja 70° väliin jäävän pinta-alan.

Pinta on osa pallopintaa, joten käytetään pallakordinaatimuunnostaa.

Huom. Muunnoksessa leikkuva θ mitataan z -akselista.

Parametrisoidaan pinta

$$\begin{cases} x = R \sin \theta \cos \phi \\ y = R \sin \theta \sin \phi \\ z = R \cos \theta \end{cases} \quad \begin{array}{l} R = \text{vakio, koska ollaan pallopinnalla} \\ \phi \in [0, 2\pi[\\ \theta \in [90^\circ - 70^\circ, 90^\circ - 60^\circ] = [\frac{\pi}{9}, \frac{\pi}{6}] \end{array}$$

$$\vec{r}(\theta, \phi) = R \sin \theta \cos \phi \hat{i} + R \sin \theta \sin \phi \hat{j} + R \cos \theta \hat{k}$$

$$\frac{\partial \vec{r}}{\partial \theta} = R \cos \theta \cos \phi \hat{i} + R \cos \theta \sin \phi \hat{j} - R \sin \theta \hat{k}$$

$$\frac{\partial \vec{r}}{\partial \phi} = -R \sin \theta \sin \phi \hat{i} + R \sin \theta \cos \phi \hat{j}$$

$$\frac{\partial \vec{r}}{\partial \theta} \times \frac{\partial \vec{r}}{\partial \phi} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ R \cos \theta \cos \phi & R \cos \theta \sin \phi & -R \sin \theta \\ -R \sin \theta \sin \phi & R \sin \theta \cos \phi & 0 \end{vmatrix}$$

$$= -R^2 \sin^2 \theta \cos \phi \hat{i} + R^2 \sin^2 \theta \sin \phi \hat{j} + \hat{k} (R^2 \sin \theta \cos \phi \cos \theta + R^2 \sin^2 \theta \sin \theta)$$

$$\left| \frac{\partial \vec{r}}{\partial \theta} \times \frac{\partial \vec{r}}{\partial \phi} \right| = \left(R^4 \sin^4 \theta \cos^2 \phi + R^4 \sin^4 \theta \sin^2 \phi + R^4 \sin^2 \theta \cos^2 \theta \right)^{1/2}$$

$$= R^2 (\sin^4 \theta + \sin^2 \theta \cos^2 \theta)^{1/2} = R^2 \sin \theta \geq 0 \quad \text{kun } \theta \in [0, \pi]$$

$$\begin{aligned}
 \boxed{3.} \quad A_1 &= \int ds = \int d\phi \int_{\frac{\pi}{9}}^{\frac{\pi}{6}} d\theta R^2 \underbrace{\sin\theta}_{|J|} = 2\pi R^2 \left[-\cos\theta \right]_{\frac{\pi}{9}}^{\frac{\pi}{6}} \\
 A_1 &= 2\pi R^2 \left(\cos\left(\frac{\pi}{9}\right) - \cos\left(\frac{\pi}{6}\right) \right)
 \end{aligned}$$

Väljin jäärvän pinta-alan osuus koko pinta-alasta on

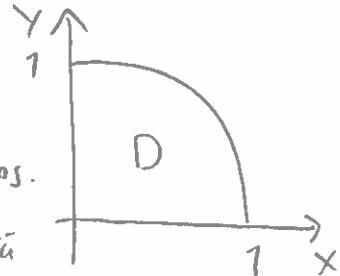
$$\textcircled{O} \quad \frac{A_1}{4\pi R^2} = \frac{1}{2} \left(\cos\left(\frac{\pi}{9}\right) - \cos\left(\frac{\pi}{6}\right) \right) \approx 3,7\%$$

4.

$$\int_D ds \arctan\left(\frac{y}{x}\right)$$

D

$$D = \{0 \leq x \leq 1, 0 \leq y \leq \sqrt{1-x^2}\}$$



Tehdään napakoordinaatimuunnos.

Parametrisaatio kuten tehtävässä

2, mutta $r \in [0,1]$ ja $\theta \in [0, \frac{\pi}{2}]$ Nyt $x = r \cos \theta$, $y = r \sin \theta$ ja $|s| = r$.

$$\begin{aligned} \Rightarrow \int_D ds \arctan\left(\frac{y}{x}\right) &= \int_0^1 dr \int_0^{\frac{\pi}{2}} d\theta r \cdot \underbrace{\arctan\left(\frac{r \sin \theta}{r \cos \theta}\right)}_{=\theta} \\ &= \int_0^1 dr r \int_0^{\frac{\pi}{2}} d\theta \theta = \int_0^1 dr r \underbrace{\int_0^{\frac{\pi}{2}} \frac{1}{2} \theta^2}_{\frac{\pi^2}{8}} = \frac{\pi^2}{8} \int_0^1 \frac{1}{2} r^2 = \frac{\pi^2}{16}. \end{aligned}$$