

Vektorianalyysi

k. 2014

Harjoitus 5

Käsitellään ke 9.4.

- Mitä geometrisia objekteja xyz -avaruudessa vastaavat ne pisteet, joiden pallokoordinaateille pätee
 - $r =$ vakio,
 - $\phi =$ vakio,
 - $\theta =$ vakio,
 - $r =$ vakio ja $\phi =$ vakio,
 - $r =$ vakio ja $\theta =$ vakio,
 - $\phi =$ vakio ja $\theta =$ vakio,
 - $r =$ vakio, $\phi =$ vakio ja $\theta =$ vakio?
- Tarkastellaan avaruuden pistettä P , jonka koordinaatit ovat $(x, y, z) = (1, 1, 1)$. Mitkä ovat tähän pisteeseen asetettujen paikallisten sylinteri- ja pallokoordinaatistojen kantavektorit $\hat{\rho}, \hat{\phi}, \hat{z}$ ja $\hat{r}, \hat{\theta}, \hat{\phi}$ xyz -koordinaatiston kantavektoreiden \hat{i}, \hat{j} ja \hat{k} avulla lausuttuina?
- Johda napakoordinaatistossa skalaarifunktion $u(r, \theta)$ gradientti ja vektorifunktion $\vec{v} = v_r(r, \theta)\hat{r} + v_\theta(r, \theta)\hat{\theta}$ divergensi $\nabla \cdot \vec{v}$.
- Osoita, että sylinterikoordinaatistossa

$$\nabla^2 u(r, \phi, z) = \frac{\partial^2 u}{\partial \rho^2} + \frac{1}{\rho} \frac{\partial u}{\partial \rho} + \frac{1}{\rho^2} \frac{\partial^2 u}{\partial \phi^2} + \frac{\partial^2 u}{\partial z^2}$$

lähtemällä Laplacen operaattorin karteesisesta lausekkeesta $\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$

ja soveltamalla derivoinnin ketjusääntöä.

- Johda vektorikentän $\vec{F} = F_r \hat{r} + F_\theta \hat{\theta} + F_\phi \hat{\phi}$ divergensi $\nabla \cdot \vec{F}$ pallokoordinaatistossa eli

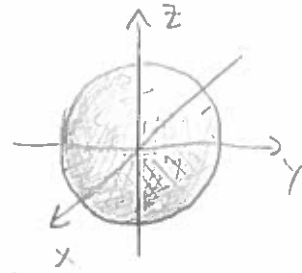
$$\nabla \cdot \vec{F} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 F_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (F_\theta \sin \theta) + \frac{1}{\rho \sin \theta} \frac{\partial F_\phi}{\partial \phi}$$

osittaisderivointia käyttäen lähtemällä muodosta (ks. luennot s. 66)

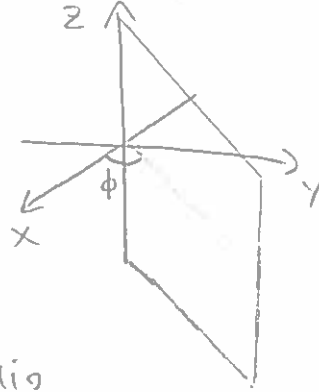
$$\nabla \cdot \vec{F} = (\hat{i} \partial_x + \hat{j} \partial_y + \hat{k} \partial_z) \cdot (F_r \hat{r} + F_\theta \hat{\theta} + F_\phi \hat{\phi}).$$

1.

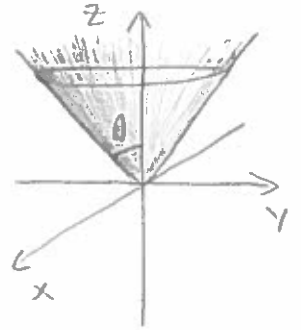
- a.) $r = \text{vakio} \Rightarrow$ pallakuori
Huom. Jos $r=0 \Rightarrow$ piste



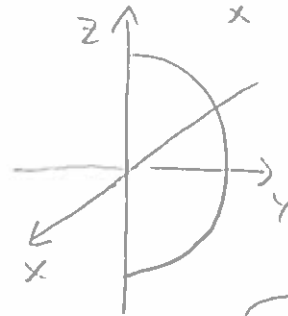
- b.) $\phi = \text{vakio} \Rightarrow$ puolitaso



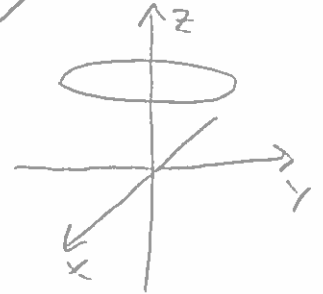
- c.) $\theta = \text{vakio} \Rightarrow$ ympyräkartioiden
Huom. Jos $\theta = \frac{\pi}{2} \Rightarrow$ taso



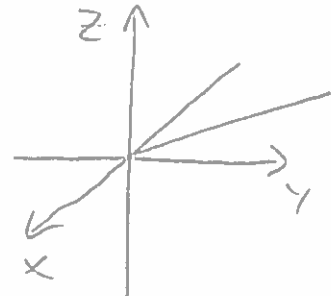
- d.) $r = \text{vakio}$ ja $\phi = \text{vakio} \Rightarrow$ puoliympyrän
 kehä
Huom. Jos $r=0 \Rightarrow$ piste



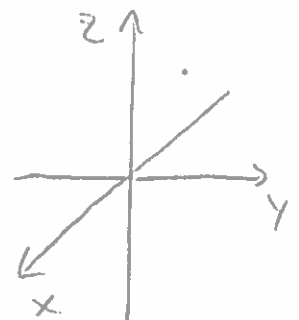
- e.) $r = \text{vakio}$ ja $\theta = \text{vakio} \Rightarrow$ ympyrän
 kehä
Huom. Jos $r=0 \Rightarrow$ piste



- f.) $\phi = \text{vakio}$ ja $\theta = \text{vakio} \Rightarrow$ puolisuora



- g.) $r = \text{vakio}$, $\phi = \text{vakio}$ ja $\theta = \text{vakio} \Rightarrow$ piste



2. Lasketaan sylinterikoordinaatiston yksikkövektorit:

$$\vec{r}(\rho, \phi, z) = \rho \cos \phi \hat{i} + \rho \sin \phi \hat{j} + z \hat{k}$$

$$\frac{\partial \vec{r}}{\partial \rho} = \cos \phi \hat{i} + \sin \phi \hat{j}, \quad \left| \frac{\partial \vec{r}}{\partial \rho} \right| = 1 = h_\rho \Rightarrow \hat{\rho} = \cos \phi \hat{i} + \sin \phi \hat{j}$$

$$\frac{\partial \vec{r}}{\partial \phi} = -\rho \sin \phi \hat{i} + \rho \cos \phi \hat{j}, \quad \left| \frac{\partial \vec{r}}{\partial \phi} \right| = \rho = h_\phi \Rightarrow \hat{\phi} = -\sin \phi \hat{i} + \cos \phi \hat{j}$$

$$\frac{\partial \vec{r}}{\partial z} = \hat{k}, \quad \left| \frac{\partial \vec{r}}{\partial z} \right| = 1 = h_z \Rightarrow \hat{z} = \hat{k}$$

○ Lasketaan pallokoordinaatiston yksikkövektorit:

$$\vec{r}(r, \phi, \theta) = r \sin \theta \cos \phi \hat{i} + r \sin \theta \sin \phi \hat{j} + r \cos \theta \hat{k}$$

$$\frac{\partial \vec{r}}{\partial r} = \sin \theta \cos \phi \hat{i} + \sin \theta \sin \phi \hat{j} + \cos \theta \hat{k} = \hat{r}$$

$$\left| \frac{\partial \vec{r}}{\partial r} \right| = (\sin^2 \theta \cos^2 \phi + \sin^2 \theta \sin^2 \phi + \cos^2 \theta)^{1/2} = 1 = h_r$$

$$\frac{\partial \vec{r}}{\partial \phi} = -r \sin \theta \sin \phi \hat{i} + r \sin \theta \cos \phi \hat{j}$$

$$\left| \frac{\partial \vec{r}}{\partial \phi} \right| = (r^2 \sin^2 \theta \sin^2 \phi + r^2 \sin^2 \theta \cos^2 \phi)^{1/2} = r \sin \theta = h_\phi$$

$$\Rightarrow \hat{\phi} = -\sin \phi \hat{i} + \cos \phi \hat{j}$$

$$\frac{\partial \vec{r}}{\partial \theta} = r \cos \theta \cos \phi \hat{i} + r \cos \theta \sin \phi \hat{j} - r \sin \theta \hat{k}$$

$$\left| \frac{\partial \vec{r}}{\partial \theta} \right| = (r^2 \cos^2 \theta \cos^2 \phi + r^2 \cos^2 \theta \sin^2 \phi + r^2 \sin^2 \theta)^{1/2} = r = h_\theta$$

$$\Rightarrow \hat{\theta} = \cos \theta \cos \phi \hat{i} + \cos \theta \sin \phi \hat{j} - \sin \theta \hat{k}$$



Piste $(x, y, z) = (1, 1, 1)$

Sylinterikoord.

$$(r, \phi, z) = (\sqrt{2}, \frac{\pi}{4}, 1)$$

$$\hat{\rho} = \frac{1}{\sqrt{2}} \hat{i} + \frac{1}{\sqrt{2}} \hat{j}$$

$$\hat{\phi} = -\frac{1}{\sqrt{2}} \hat{i} + \frac{1}{\sqrt{2}} \hat{j}$$

$$\hat{z} = \hat{k}$$

Pallokoord.

$$(r, \phi, \theta) = (\sqrt{3}, \frac{\pi}{4}, \tan^{-1} \sqrt{2})$$

$$\hat{r} = \frac{\sqrt{2}}{\sqrt{3}} \cdot \frac{1}{\sqrt{2}} \hat{i} + \frac{\sqrt{2}}{\sqrt{3}} \cdot \frac{1}{\sqrt{2}} \hat{j} + \frac{1}{\sqrt{3}} \hat{k} = \frac{1}{\sqrt{3}} (\hat{i} + \hat{j} + \hat{k})$$

$$\hat{\phi} = \frac{1}{\sqrt{2}} (-\hat{i} + \hat{j})$$

$$\hat{\theta} = \frac{1}{\sqrt{3}} \cdot \frac{1}{\sqrt{2}} \hat{i} + \frac{1}{\sqrt{3}} \cdot \frac{1}{\sqrt{2}} \hat{j} - \frac{\sqrt{2}}{\sqrt{3}} \hat{k} = \frac{1}{\sqrt{6}} (\hat{i} + \hat{j} - 2\hat{k})$$

$$\begin{aligned} x &= r \cos \theta \\ y &= r \sin \theta \end{aligned}$$

3.

$$u(r, \theta), \quad \vec{v} = v_r(r, \theta) \hat{r} + v_\theta(r, \theta) \hat{\theta}$$

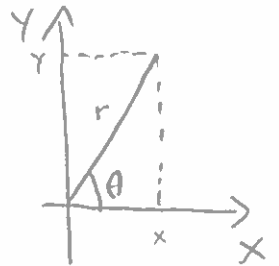
$$\begin{aligned} \nabla u &= (\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y}) u = \hat{i} \left(\frac{\partial u}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial u}{\partial \theta} \frac{\partial \theta}{\partial x} \right) + \hat{j} \left(\frac{\partial u}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial u}{\partial \theta} \frac{\partial \theta}{\partial y} \right) \\ &= \frac{\partial u}{\partial r} \left(\hat{i} \frac{\partial r}{\partial x} + \hat{j} \frac{\partial r}{\partial y} \right) + \frac{\partial u}{\partial \theta} \left(\hat{i} \frac{\partial \theta}{\partial x} + \hat{j} \frac{\partial \theta}{\partial y} \right) \end{aligned}$$

$$\begin{aligned} r &= \sqrt{x^2 + y^2} \\ \theta &= \arctan\left(\frac{y}{x}\right) \end{aligned}$$

$$\frac{x}{\sqrt{x^2+y^2}} \hat{i} + \frac{y}{\sqrt{x^2+y^2}} \hat{j} = \cos \theta \hat{i} + \sin \theta \hat{j} = \hat{r}$$

$$\frac{\partial \theta}{\partial x} = \frac{1}{\left(\frac{y}{x}\right)^2 + 1} \cdot \left(-\frac{y}{x^2}\right) = -\frac{y}{y^2+x^2} = -\frac{y}{r^2} = -\frac{\sin \theta}{r}$$

$$\frac{\partial \theta}{\partial y} = \frac{1}{\left(\frac{y}{x}\right)^2 + 1} \cdot \frac{1}{x} = \frac{x}{y^2+x^2} = \frac{x}{r^2} = \frac{\cos \theta}{r}$$



$$\Rightarrow \hat{i} \frac{\partial \theta}{\partial x} + \hat{j} \frac{\partial \theta}{\partial y} = \frac{1}{r} \left(-\frac{y}{r} \hat{i} + \frac{x}{r} \hat{j} \right) = \frac{1}{r} \hat{\theta}$$

$$\Rightarrow \nabla u = \frac{\partial u}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial u}{\partial \theta} \hat{\theta}$$

○

Etsiä $\nabla \cdot \vec{v}_r$? $\nabla = \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} = \hat{i} \left(\frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial}{\partial \theta} \right) + \hat{j} \left(\frac{\partial r}{\partial y} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial y} \frac{\partial}{\partial \theta} \right)$

$$\begin{aligned} \vec{v} &= v_r \hat{r} + v_\theta \hat{\theta} = v_r (\cos \theta \hat{i} + \sin \theta \hat{j}) + v_\theta (-\sin \theta \hat{i} + \cos \theta \hat{j}) \\ &= (v_r \cos \theta - v_\theta \sin \theta) \hat{i} + (v_r \sin \theta + v_\theta \cos \theta) \hat{j} \end{aligned}$$

$$\begin{aligned} \Rightarrow \nabla \cdot \vec{v} &= \underbrace{\left(\frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial}{\partial \theta} \right)}_{x\text{-derivaatta}} \underbrace{(v_r \cos \theta - v_\theta \sin \theta)}_{x\text{-komponentti}} + \underbrace{\left(\frac{\partial r}{\partial y} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial y} \frac{\partial}{\partial \theta} \right)}_{y\text{-derivaatta}} \underbrace{(v_r \sin \theta + v_\theta \cos \theta)}_{y\text{-komponentti}} \\ &= \frac{\partial r}{\partial x} \left(\cos \theta \frac{\partial v_r}{\partial r} - \sin \theta \frac{\partial v_\theta}{\partial r} \right) + \frac{\partial \theta}{\partial x} \left(\frac{\partial v_r}{\partial \theta} \cos \theta - \sin \theta v_r - \frac{\partial v_\theta}{\partial \theta} \sin \theta - v_\theta \cos \theta \right) \\ &\quad + \frac{\partial r}{\partial y} \left(\sin \theta \frac{\partial v_r}{\partial r} + \cos \theta \frac{\partial v_\theta}{\partial r} \right) + \frac{\partial \theta}{\partial y} \left(\frac{\partial v_r}{\partial \theta} \sin \theta + v_r \cos \theta + \frac{\partial v_\theta}{\partial \theta} \cos \theta - v_\theta \sin \theta \right) \end{aligned}$$

3.

$$\begin{aligned}
 &= \frac{\partial V_r}{\partial r} \left(\frac{\partial r}{\partial x} \cos \theta + \frac{\partial r}{\partial y} \sin \theta \right) + \frac{\partial V_\theta}{\partial r} \left(-\frac{\partial r}{\partial x} \sin \theta + \frac{\partial r}{\partial y} \cos \theta \right) \\
 &+ \frac{\partial V_r}{\partial \theta} \left(\frac{\partial \theta}{\partial x} \cos \theta + \frac{\partial \theta}{\partial y} \sin \theta \right) + \frac{\partial V_\theta}{\partial \theta} \left(-\frac{\partial \theta}{\partial x} \sin \theta + \frac{\partial \theta}{\partial y} \cos \theta \right) \\
 &+ V_r \left(-\frac{\partial \theta}{\partial x} \sin \theta + \frac{\partial \theta}{\partial y} \cos \theta \right) + V_\theta \left(-\frac{\partial \theta}{\partial x} \cos \theta - \frac{\partial \theta}{\partial y} \sin \theta \right) \\
 &= \frac{\partial V_r}{\partial r} \left(\cos^2 \theta + \sin^2 \theta \right) + \frac{\partial V_\theta}{\partial r} \left(-\cos \theta \sin \theta + \sin \theta \cos \theta \right) \\
 &+ \frac{\partial V_r}{\partial \theta} \left(-\frac{\sin \theta}{r} \cos \theta + \frac{\cos \theta}{r} \sin \theta \right) + \frac{\partial V_\theta}{\partial \theta} \left(\frac{\sin^2 \theta}{r} + \frac{\cos^2 \theta}{r} \right) \\
 &+ V_r \left(+\frac{\sin^2 \theta}{r} + \frac{\cos^2 \theta}{r} \right) + V_\theta \left(\frac{\sin \theta \cos \theta}{r} - \frac{\cos \theta \sin \theta}{r} \right) \\
 &= \frac{\partial V_r}{\partial r} + \frac{1}{r} \frac{\partial V_\theta}{\partial \theta} + \frac{1}{r} V_r = \frac{1}{r} \cdot r \frac{\partial V_r}{\partial r} + \frac{1}{r} \frac{\partial r}{\partial r} V_r + \frac{1}{r} \frac{\partial V_\theta}{\partial \theta} \\
 &= \frac{1}{r} \frac{\partial (r V_r)}{\partial r} + \frac{1}{r} \frac{\partial V_\theta}{\partial \theta}
 \end{aligned}$$

4.

Näytä, että sylinterikoordinaatissa,

$$\nabla^2 u(r, \phi, z) = \frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \phi^2} + \frac{\partial^2 u}{\partial z^2}, \text{ kun}$$

$$\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

 1^o $\frac{\partial^2 u}{\partial z^2}$ pysyy sellaisenaan.

$$\begin{cases} r = \sqrt{x^2 + y^2} \\ \phi = \arctan\left(\frac{y}{x}\right) \\ x = r \cos \phi \\ y = r \sin \phi \end{cases}$$

$$2^{\circ} \frac{\partial^2 u}{\partial x^2} = \frac{\partial}{\partial x} \frac{\partial u}{\partial x}, \quad \frac{\partial}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \phi}{\partial x} \frac{\partial}{\partial \phi} \quad \Leftarrow \text{ketjusääntö}$$

$$\frac{\partial u}{\partial x} = \left(\frac{x}{\sqrt{x^2 + y^2}} \frac{\partial}{\partial r} - \frac{1}{\left(\frac{y}{x}\right)^2 + 1} \cdot \frac{y}{x^2} \frac{\partial}{\partial \phi} \right) u = \left(\cos \phi \frac{\partial}{\partial r} - \frac{\sin \phi}{r} \frac{\partial}{\partial \phi} \right) u$$

$$= \cos \phi \frac{\partial u}{\partial r} - \frac{\sin \phi}{r} \frac{\partial u}{\partial \phi}$$

$$\frac{\partial^2 u}{\partial x^2} = \left(\cos \phi \frac{\partial}{\partial r} - \frac{\sin \phi}{r} \frac{\partial}{\partial \phi} \right) \left(\cos \phi \frac{\partial u}{\partial r} - \frac{\sin \phi}{r} \frac{\partial u}{\partial \phi} \right)$$

$$= \cos^2 \phi \frac{\partial^2 u}{\partial r^2} - \cos \phi \sin \phi \left(-\frac{1}{r^2} \frac{\partial u}{\partial \phi} + \frac{1}{r} \frac{\partial^2 u}{\partial r \partial \phi} \right)$$

$$- \frac{\sin \phi}{r} \left(-\sin \phi \frac{\partial u}{\partial r} + \cos \phi \frac{\partial^2 u}{\partial \phi \partial r} \right) + \frac{\sin \phi}{r^2} \left(\cos \phi \frac{\partial u}{\partial \phi} + \sin \phi \frac{\partial^2 u}{\partial \phi^2} \right)$$

$$= \cos^2 \phi \frac{\partial^2 u}{\partial r^2} + \frac{\cos \phi \sin \phi}{r^2} \frac{\partial u}{\partial \phi} - \frac{\cos \phi \sin \phi}{r} \frac{\partial^2 u}{\partial r \partial \phi}$$

$$+ \frac{\sin^2 \phi}{r} \frac{\partial u}{\partial r} - \frac{\sin \phi \cos \phi}{r} \frac{\partial^2 u}{\partial \phi \partial r} + \frac{\sin \phi \cos \phi}{r^2} \frac{\partial u}{\partial \phi} + \frac{\sin^2 \phi}{r^2} \frac{\partial^2 u}{\partial \phi^2}$$

$$= \cos^2 \phi \frac{\partial^2 u}{\partial r^2} + \frac{\sin^2 \phi}{r} \frac{\partial u}{\partial r} + \frac{2 \cos \phi \sin \phi}{r^2} \frac{\partial u}{\partial \phi} - \frac{2 \cos \phi \sin \phi}{r} \frac{\partial^2 u}{\partial r \partial \phi}$$

$$+ \frac{\sin^2 \phi}{r^2} \frac{\partial^2 u}{\partial \phi^2}$$

4.

$$3^o \quad \frac{\partial^2 u}{\partial y^2} = \frac{\partial}{\partial y} \frac{\partial u}{\partial y}, \quad \frac{\partial}{\partial y} = \frac{\partial r}{\partial y} \frac{\partial}{\partial r} + \frac{\partial \phi}{\partial y} \frac{\partial}{\partial \phi}$$

$$\frac{\partial u}{\partial y} = \left(\frac{y}{\sqrt{x^2+y^2}} \frac{\partial}{\partial r} + \frac{1}{\left(\frac{y}{x}\right)^2+1} \cdot \frac{1}{x} \frac{\partial}{\partial \phi} \right) u = \left(\frac{y}{\sqrt{x^2+y^2}} \frac{\partial}{\partial r} + \frac{x}{y^2+x^2} \frac{\partial}{\partial \phi} \right) u$$

$$= \left(\sin \phi \frac{\partial}{\partial r} + \frac{\cos \phi}{r} \frac{\partial}{\partial \phi} \right) u = \sin \phi \frac{\partial u}{\partial r} + \frac{\cos \phi}{r} \frac{\partial u}{\partial \phi}$$

$$\frac{\partial^2 u}{\partial y^2} = \left(\sin \phi \frac{\partial}{\partial r} + \frac{\cos \phi}{r} \frac{\partial}{\partial \phi} \right) \left(\sin \phi \frac{\partial u}{\partial r} + \frac{\cos \phi}{r} \frac{\partial u}{\partial \phi} \right)$$

$$= \sin^2 \phi \frac{\partial^2 u}{\partial r^2} + \sin \phi \cos \phi \left(-\frac{1}{r^2} \frac{\partial u}{\partial \phi} + \frac{1}{r} \frac{\partial^2 u}{\partial r \partial \phi} \right)$$

$$+ \frac{\cos \phi}{r} \left(\cos \phi \frac{\partial u}{\partial r} + \sin \phi \frac{\partial^2 u}{\partial \phi \partial r} \right) + \frac{\cos \phi}{r^2} \left(-\sin \phi \frac{\partial u}{\partial \phi} + \cos \phi \frac{\partial^2 u}{\partial \phi^2} \right)$$

$$= \sin^2 \phi \frac{\partial^2 u}{\partial r^2} - \frac{\sin \phi \cos \phi}{r^2} \frac{\partial u}{\partial \phi} + \frac{\sin \phi \cos \phi}{r} \frac{\partial^2 u}{\partial r \partial \phi} + \frac{\cos^2 \phi}{r} \frac{\partial u}{\partial r}$$

$$+ \frac{\cos \phi \sin \phi}{r} \frac{\partial^2 u}{\partial \phi \partial r} - \frac{\cos \phi \sin \phi}{r^2} \frac{\partial u}{\partial \phi} + \frac{\cos^2 \phi}{r^2} \frac{\partial^2 u}{\partial \phi^2}$$

$$= \sin^2 \phi \frac{\partial^2 u}{\partial r^2} - \frac{2 \sin \phi \cos \phi}{r^2} \frac{\partial u}{\partial \phi} + \frac{2 \sin \phi \cos \phi}{r} \frac{\partial^2 u}{\partial r \partial \phi} + \frac{\cos^2 \phi}{r} \frac{\partial u}{\partial r}$$

$$+ \frac{\cos^2 \phi}{r^2} \frac{\partial^2 u}{\partial \phi^2}$$

$$\Rightarrow \nabla^2 u = \cos^2 \phi \frac{\partial^2 u}{\partial r^2} + \sin^2 \phi \frac{\partial^2 u}{\partial r^2} + \frac{\sin^2 \phi}{r} \frac{\partial u}{\partial r} + \frac{\cos^2 \phi}{r} \frac{\partial u}{\partial r}$$

$$+ \frac{\sin^2 \phi}{r^2} \frac{\partial^2 u}{\partial \phi^2} + \frac{\cos^2 \phi}{r^2} \frac{\partial^2 u}{\partial \phi^2} + \frac{\partial^2 u}{\partial z^2}$$

$$= \frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \phi^2} + \frac{\partial^2 u}{\partial z^2}$$

Jeit!

5. Oik. $\vec{F} = F_r \hat{r} + F_\theta \hat{\theta} + F_\phi \hat{\phi}$. Näytä, että

$$\nabla \cdot \vec{F} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 F_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (F_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial F_\phi}{\partial \phi}$$

$$\nabla = \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} = \hat{i} \left(\frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial}{\partial \theta} + \frac{\partial \phi}{\partial x} \frac{\partial}{\partial \phi} \right)$$

$$+ \hat{j} \left(\frac{\partial r}{\partial y} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial y} \frac{\partial}{\partial \theta} + \frac{\partial \phi}{\partial y} \frac{\partial}{\partial \phi} \right) + \hat{k} \left(\frac{\partial r}{\partial z} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial z} \frac{\partial}{\partial \theta} + \frac{\partial \phi}{\partial z} \frac{\partial}{\partial \phi} \right)$$

$$r = (x^2 + y^2 + z^2)^{1/2}$$

$$\frac{\partial r}{\partial x} = \frac{x}{\sqrt{x^2 + y^2 + z^2}} = \cos \phi \sin \theta$$

$$\theta = \arctan \left(\frac{\sqrt{x^2 + y^2}}{z} \right)$$

$$\frac{\partial r}{\partial y} = \frac{y}{\sqrt{x^2 + y^2 + z^2}} = \sin \phi \sin \theta$$

$$\phi = \arctan \left(\frac{y}{x} \right)$$

$$\frac{\partial r}{\partial z} = \frac{z}{\sqrt{x^2 + y^2 + z^2}} = \cos \theta$$

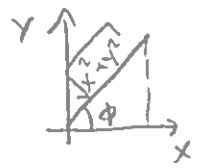
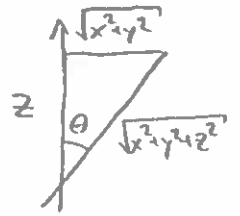
$$\frac{\partial \theta}{\partial x} = \frac{1}{\frac{x^2 + y^2}{z^2} + 1} \cdot \frac{1}{z} \cdot \frac{x}{\sqrt{x^2 + y^2}} = \frac{z}{x^2 + y^2 + z^2} \cdot \frac{x}{\sqrt{x^2 + y^2}} = \frac{\cos \theta \cos \phi}{r}$$

$$\frac{\partial \theta}{\partial y} = \frac{z}{x^2 + y^2 + z^2} \cdot \frac{y}{\sqrt{x^2 + y^2}} = \frac{\cos \theta \sin \phi}{r}$$

$$\frac{\partial \theta}{\partial z} = \frac{1}{\frac{x^2 + y^2}{z^2} + 1} \cdot \left(-\frac{\sqrt{x^2 + y^2}}{z^2} \right) = -\frac{\sqrt{x^2 + y^2}}{x^2 + y^2 + z^2} = -\frac{\sin \theta}{r}$$

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= \frac{1}{\left(\frac{y}{x}\right)^2 + 1} \left(-\frac{y}{x^2} \right) = -\frac{y}{y^2 + x^2} = -\frac{\sin \phi}{\sqrt{y^2 + x^2}} = -\frac{\sin \phi}{\sqrt{r^2 \sin^2 \theta \sin^2 \phi + r^2 \cos^2 \phi \sin^2 \theta}} \\ &= -\frac{\sin \phi}{r \sin \theta} \end{aligned}$$

$$\frac{\partial \phi}{\partial y} = \frac{1}{\left(\frac{y}{x}\right)^2 + 1} \cdot \frac{1}{x} = \frac{x}{y^2 + x^2} = \frac{\cos \phi}{r \sin \theta}, \quad \frac{\partial \phi}{\partial z} = 0.$$



5. Esitetään \vec{F} vektorien \hat{i} , \hat{j} ja \hat{k} avulla.

$$\vec{F} = F_r \underbrace{(\sin\theta \cos\phi \hat{i} + \sin\theta \sin\phi \hat{j} + \cos\theta \hat{k})}_{\hat{r} \text{ (ks. teht. 2)}} + F_\theta \underbrace{(\cos\theta \cos\phi \hat{i} + \cos\theta \sin\phi \hat{j} - \sin\theta \hat{k})}_{\hat{\theta}}$$

$$+ F_\phi \underbrace{(-\sin\phi \hat{i} + \cos\phi \hat{j})}_{\hat{\phi}}$$

$$= (F_r \sin\theta \cos\phi + F_\theta \cos\theta \cos\phi - F_\phi \sin\phi) \hat{i}$$

$$+ (F_r \sin\theta \sin\phi + F_\theta \cos\theta \sin\phi + F_\phi \cos\phi) \hat{j}$$

$$+ (F_r \cos\theta - F_\theta \sin\theta) \hat{k}$$

$$= F_x \hat{i} + F_y \hat{j} + F_z \hat{k}$$

$$\frac{\partial F_x}{\partial x} = \left(\frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial}{\partial \theta} + \frac{\partial \phi}{\partial x} \frac{\partial}{\partial \phi} \right) F_x = (\cos\phi \sin\theta)$$

$$= \left(\cos\phi \sin\theta \frac{\partial}{\partial r} + \frac{\cos\theta \cos\phi}{r} \frac{\partial}{\partial \theta} - \frac{\sin\phi}{r \sin\theta} \frac{\partial}{\partial \phi} \right) \cdot$$

$$(F_r \sin\theta \cos\phi + F_\theta \cos\theta \cos\phi - F_\phi \sin\phi)$$

$$= \cos^2\phi \sin^2\theta \frac{\partial F_r}{\partial r} + \cos^2\phi \sin\theta \cos\theta \frac{\partial F_\theta}{\partial r} - \cos\phi \sin\theta \sin\phi \frac{\partial F_\phi}{\partial r}$$

$$+ \frac{\cos\theta \cos^2\phi}{r} \left(\frac{\partial F_r}{\partial \theta} \sin\theta + F_r \cos\theta \right) + \frac{\cos\theta \cos^2\phi}{r} \left(\frac{\partial F_\theta}{\partial \theta} \cos\theta - F_\theta \sin\theta \right)$$

$$- \frac{\cos\theta \cos\phi \sin\phi}{r} \frac{\partial F_\phi}{\partial \theta}$$

$$- \frac{\sin\phi}{r} \left(\frac{\partial F_r}{\partial \phi} \cos\phi - F_r \sin\phi \right) - \frac{\sin\phi \cos\theta}{r \sin\theta} \left(\frac{\partial F_\theta}{\partial \phi} \cos\phi - F_\theta \sin\phi \right)$$

$$+ \frac{\sin\phi}{r \sin\theta} \left(\frac{\partial F_\phi}{\partial \phi} \sin\phi + F_\phi \cos\phi \right)$$

$$\begin{aligned}
 \boxed{5.} \quad \frac{\partial F_y}{\partial y} &= \left(\frac{\partial r}{\partial y} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial y} \frac{\partial}{\partial \theta} + \frac{\partial \phi}{\partial y} \frac{\partial}{\partial \phi} \right) F_y \\
 &= \left(\sin \phi \sin \theta \frac{\partial}{\partial r} + \frac{\cos \theta \sin \phi}{r} \frac{\partial}{\partial \theta} + \frac{\cos \phi}{r \sin \theta} \frac{\partial}{\partial \phi} \right) \cdot \\
 &\quad \left(F_r \sin \theta \sin \phi + F_\theta \cos \theta \sin \phi + F_\phi \cos \phi \right) \\
 &= \sin^2 \phi \sin^2 \theta \frac{\partial F_r}{\partial r} + \sin^2 \phi \sin \theta \cos \theta \frac{\partial F_\theta}{\partial r} + \sin \theta \sin \phi \cos \phi \frac{\partial F_\phi}{\partial r} \\
 &\quad + \frac{\cos \theta \sin^2 \phi}{r} \left(\frac{\partial F_r}{\partial \theta} \sin \theta + F_r \cos \theta \right) + \frac{\cos \theta \sin^2 \phi}{r} \left(\frac{\partial F_\theta}{\partial \theta} \cos \theta - F_\theta \sin \theta \right) \\
 &\quad + \frac{\cos \theta \sin \phi \cos \phi}{r} \frac{\partial F_\phi}{\partial \theta} \\
 &\quad + \frac{\cos \phi}{r} \left(\frac{\partial F_r}{\partial \phi} \sin \phi + F_r \cos \phi \right) + \frac{\cos \phi \cos \theta}{r \sin \theta} \left(\frac{\partial F_\theta}{\partial \phi} \sin \phi + F_\theta \cos \phi \right) \\
 &\quad + \frac{\cos \phi}{r \sin \theta} \left(\frac{\partial F_\phi}{\partial \phi} \cos \phi - F_\phi \sin \phi \right)
 \end{aligned}$$

$$\begin{aligned}
 \frac{\partial F_z}{\partial z} &= \left(\frac{\partial r}{\partial z} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial z} \frac{\partial}{\partial \theta} + \frac{\partial \phi}{\partial z} \frac{\partial}{\partial \phi} \right) F_z \\
 &= \left(\cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \right) \cdot \left(F_r \cos \theta - F_\theta \sin \theta \right) \\
 &= \cos^2 \theta \frac{\partial F_r}{\partial r} - \cos \theta \sin \theta \frac{\partial F_\theta}{\partial r} - \frac{\sin \theta}{r} \left(\frac{\partial F_r}{\partial \theta} \cos \theta - F_r \sin \theta \right) \\
 &\quad + \frac{\sin \theta}{r} \left(\frac{\partial F_\theta}{\partial \theta} \sin \theta + F_\theta \cos \theta \right)
 \end{aligned}$$

Kasataan sitten tulokset.

5.

$$\begin{aligned}
\frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} + \frac{\partial F_z}{\partial z} &= \frac{\partial F_r}{\partial r} \left(\cos^2 \phi \sin^2 \theta + \sin^2 \phi \sin^2 \theta + \cos^2 \theta \right) && \text{OK} \\
+ \frac{\partial F_\theta}{\partial r} \left(\cos^2 \phi \sin \theta \cos \theta + \sin^2 \phi \sin \theta \cos \theta - \cos \theta \sin \theta \right) &&& \text{OK (=0)} \\
+ \frac{\partial F_\phi}{\partial r} \left(-\cos \phi \sin \theta \sin \phi + \sin \theta \sin \phi \cos \phi \right) &&& \text{OK (=0)} \\
+ \frac{\partial F_r}{\partial \theta} \left(\frac{\cos \theta \sin \theta \cos^2 \phi}{r} + \frac{\cos \theta \sin \theta \sin^2 \phi}{r} - \frac{\sin \theta \cos \theta}{r} \right) &&& \text{OK (=0)} \\
+ F_r \left(\frac{\cos^2 \theta \cos^2 \phi}{r} + \frac{\cos^2 \theta \sin^2 \phi}{r} + \frac{\sin^2 \theta}{r} \right) &&& \text{OK} \\
+ \frac{\partial F_\theta}{\partial \theta} \left(\frac{\cos^2 \theta \cos^2 \phi}{r} + \frac{\cos^2 \theta \sin^2 \phi}{r} + \frac{\sin^2 \theta}{r} \right) &&& \text{OK} \\
+ F_\theta \left(-\frac{\cos \theta \sin \theta \cos^2 \phi}{r} - \frac{\cos \theta \sin \theta \sin^2 \phi}{r} + \frac{\sin \theta \cos \theta}{r} \right) &&& \text{OK (=0)} \\
+ \frac{\partial F_\phi}{\partial \theta} \left(-\frac{\cos \theta \cos \phi \sin \phi}{r} + \frac{\cos \theta \sin \phi \cos \phi}{r} \right) &&& \text{OK (=0)} \\
+ \frac{\partial F_r}{\partial \phi} \left(-\frac{\sin \phi \cos \phi}{r} + \frac{\cos \phi \sin \phi}{r} \right) &&& \text{OK (=0)} \\
+ F_r \left(\frac{\sin^2 \phi}{r} + \frac{\cos^2 \phi}{r} \right) &&& \text{OK} \\
+ \frac{\partial F_\theta}{\partial \phi} \left(-\frac{\sin \phi \cos \theta \cos \phi}{r \sin \theta} + \frac{\cos \phi \cos \theta \sin \phi}{r \sin \theta} \right) &&& \text{OK (=0)} \\
+ F_\theta \left(\frac{\sin^2 \phi \cos \theta}{r \sin \theta} + \frac{\cos^2 \phi \cos \theta}{r \sin \theta} \right) &&& \text{OK} \\
+ \frac{\partial F_\phi}{\partial \phi} \left(\frac{\sin^2 \phi}{r \sin \theta} + \frac{\cos^2 \phi}{r \sin \theta} \right) &&& \text{OK} \\
+ F_\phi \left(\frac{\sin \phi \cos \phi}{r \sin \theta} - \frac{\cos \phi \sin \phi}{r \sin \theta} \right) &&& \text{OK (=0)}
\end{aligned}$$

5.

$$\begin{aligned}
&= \frac{\partial F_r}{\partial r} + \frac{1}{r} F_r + \frac{1}{r} \frac{\partial F_\theta}{\partial \theta} + \frac{1}{r} F_r + \frac{\cos \theta}{r \sin \theta} F_\theta + \frac{1}{r \sin \theta} \frac{\partial F_\phi}{\partial \phi} \\
&= \frac{\partial F_r}{\partial r} + \frac{2}{r} F_r + \frac{1}{r} \frac{\partial F_\theta}{\partial \theta} + \frac{\cos \theta}{r \sin \theta} F_\theta + \frac{1}{r \sin \theta} \frac{\partial F_\phi}{\partial \phi} \\
&= \frac{1}{r^2} \left(r^2 \frac{\partial F_r}{\partial r} + 2r F_r \right) + \frac{1}{r \sin \theta} \left(\frac{\partial F_\theta}{\partial \theta} \sin \theta + F_\theta \cos \theta \right) + \frac{1}{r \sin \theta} \frac{\partial F_\phi}{\partial \phi} \\
&= \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 F_r \right) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} \left(F_\theta \sin \theta \right) + \frac{1}{r \sin \theta} \frac{\partial F_\phi}{\partial \phi}
\end{aligned}$$

Hilpehi!

Vinkkejä pitkiin tehtäviin:

1. Jaa ongelma osiin, esim. laske termit $\frac{\partial F_x}{\partial x}$

kukin erikseen ja yhdistä saamasi tulokset

lopuksi

2. Kirjoita selkeitä kokonaisuuksia esim.

yksi asia yhdelle riville. Näin voit

jäljittää virheet helpommin.

3. Kirjoita väljästi ja jätä hiukan tilaa korjauksille.