1. Let  $\Omega \subset \mathbb{R}^N$  be a bounded domain. Suppose that  $u \in C^2(\Omega) \cap C(\overline{\Omega})$  satisfies

 $-\Delta u \leq 0$  in  $\Omega$ .

Prove that

(a)

$$u(x) \le \int_{B(x,r)} u(y) \, dy$$
 for all  $B(x,r) \Subset \Omega$ ,

(b)

$$\max_{\overline{\Omega}} u = \max_{\partial \Omega} u.$$

*Proof.* (a) Let  $x \in \Omega$ . Define

$$\phi(r) := \int_{\partial B(x,r)} \phi(y) \, dS(y)$$

for all  $0 < r < \text{dist}(x, \partial \Omega)$ . Then (see proof of Theorem 4.13)

$$\phi'(r) = \int_{B(x,r)} \Delta u(y) \, dy \ge 0.$$

Thus by the fundamental theorem of calculus we have for any  $\varepsilon \in (0, r)$ 

$$\int_{B(x,r)} u(y) \, dy = \phi(r) = \phi(\varepsilon) + \int_{\varepsilon}^{r} \phi'(s) \, ds \ge \phi(\varepsilon) = \int_{B(x,\varepsilon)} u(y) \, dy.$$

Since the right-hand side converges to u(x) as  $\varepsilon \to 0$ , we obtain the claim.

(b) Suppose that there is  $x_0 \in \Omega$  such that  $u(x_0) = M$ . Then

$$M = u(x_0) \le \int_{B(x,r)} u(y) \, dy.$$

This is possible only if  $u \equiv M$  in B(x, r). Since  $\Omega$  is open and connected, it is path-connected. Thus we can connect any two points in  $\Omega$  with a chain of balls, and so it follows that  $u \equiv M$  in  $\Omega$ .

2. Let  $\varphi : \mathbb{R} \to \mathbb{R}$  be a smooth and convex function. Assume that u is harmonic in  $\Omega$ . Let  $v = \varphi(u)$ . Prove that

$$-\Delta v \le 0$$
 in  $\Omega$ .

*Proof.* Given vectors  $\xi, \eta \in \mathbb{R}^N$ , we denote by  $\xi \otimes \eta$  the  $N \times N$  matrix whose (i, j)-entry is  $\xi_i \eta_j$ . Then by chain rule

$$Dv = \varphi'(u)Du$$
 and  $D^2v = \varphi''(u)Du \otimes Du + \varphi'(u)D^2u$ 

Thus

$$-\Delta v = -\operatorname{tr}(D^2 v) = -\sum_{i=1}^N \left(\varphi''(u)D_i u D_i u + \varphi'(u)D_{ii}u\right)$$
$$= -\sum_{i=1}^N \varphi''(u)(D_i u)^2 + \varphi'(u)D_{ii}u$$
$$= -\varphi''(u)|Du|^2 - \varphi'(u)\Delta u$$
$$\leq -\varphi'\Delta u.$$
$$= 0.$$

3. Assume that u is harmonic in  $\Omega$ . Let  $v = |Du|^2$ . Prove that

$$-\Delta v \leq 0$$
 in  $\Omega$ .

*Proof.* Recall that harmonic functions are smooth by Theorem 4.20. Therefore we can change the order of differentiation. Consequently for any  $i \in \{1, ..., N\}$  we have

$$\Delta(D_i u) = \sum_{k=1}^N D_{kk} D_i u = \sum_{k=1}^N D_i (D_{kk} u) = D_i \sum_{k=1}^N D_{kk} u = D_i (\Delta u) = 0,$$

so that  $D_i u$  is harmonic. We now let  $\varphi(s) = s^2$ . Then  $\varphi$  is convex and smooth, and thus Problem 2 implies that

$$\Delta(\varphi(D_i u)) = 0,$$

i.e.  $\varphi(D_i u)$  is harmonic. Consequently

$$-\Delta v = -\Delta(\sum_{i=1}^{N} (D_i u)^2) = \sum_{i=1}^{N} \Delta((D_i u)^2) = \sum_{i=1}^{N} \Delta(\varphi(D_i u)) = 0.$$

4. Verify by Direct calculation that

$$\Phi(x) = \begin{cases} c_2 \log(|x|), & N = 2, \\ c_N |x|^{2-N}, & N \ge 3, \end{cases}$$

is harmonic in  $\mathbb{R}^N \setminus \{0\}$ .

*Proof.* Denote r(x) = |x| so that

$$Dr(x) = \frac{x}{|x|}$$
 and  $D^2r(x) = \frac{I}{|x|} - \frac{x \otimes x}{|x|^3}$ .

Set also

$$\varphi(s) = \begin{cases} c_2 \log(s), & N = 2, \\ c_N s^{2-N}, & N \ge 3, \end{cases}$$

so that

$$\varphi'(s) = \begin{cases} \frac{c_2}{s}, & N = 2, \\ c_N(2-N)s^{1-N}, & N \ge 3, \end{cases}$$

and

$$\varphi''(s) = \begin{cases} -\frac{c_2}{s^2}, & N = 2, \\ c_N(2-N)(1-N)s^{-N}, & N \ge 3. \end{cases}$$

Then  $\Phi(x) = \varphi(r(x))$  and

$$D^{2}\Phi(x) = \varphi''(r(x))Dr(x) \otimes Dr(x) + \varphi'(r(x))D^{2}r(x).$$

Thus

$$\begin{split} \Delta \Phi(x) &= \operatorname{tr}(\varphi''(|x|)\frac{x}{|x|} \otimes \frac{x}{|x|} + \varphi'(|x|)(\frac{1}{|x|} - \frac{x \otimes x}{|x|^3}) \\ &= \varphi''(|x|)\frac{|x|^2}{|x|^2} + \varphi'(|x|)(\frac{N}{|x|} - \frac{|x|^2}{|x|^3}) \\ &= \varphi''(|x|) + \varphi'(|x|)(\frac{N-1}{|x|}) \\ &= 0. \end{split}$$

5. Let  $g \in \mathbb{R}$  and  $f: [0,\infty) \to \mathbb{R}$  be continuous. Prove that if  $u \in C^2(B_1) \cap C(\overline{B}_1)$  solves

$$\begin{cases} -\Delta u(x) = f(|x|) & \text{in } B_1, \\ u(x) = g & \text{on } \partial B_1, \end{cases}$$
(1)

then u is radially symmetric.

*Proof.* Fix  $x_0 \in B_1 \setminus \{0\}$  and let Q be an orthogonal matrix such that  $Qx_0 = |x_0|e_1$ , where  $e_1 = (1, 0, ..., 0)$ . That is  $x \mapsto Qx$  is a rotation of the coordinates that takes  $x_0$  to  $|x_0|e_1$ . Define

$$v(x) := u(Qx).$$

In exercise 3, problem 5, we proved that for all  $x \in B_1$  we have

$$D^2 v(x) = Q^T D^2 u(Qx) Q.$$

Thus, if  $x \in B_1$ , we have

$$-\Delta v(x) = -D^2 u(Qx) = f(|Qx|) = f(|x|),$$

and if  $x \in \partial B_1$ , we have

$$v(x) = u(\underbrace{Qx}_{\in \partial B_1}) = g$$

That is, v is also a solution to problem (1). But then by uniqueness (Theorem 4.19) we must have  $v \equiv u$  and in particular

$$u(x_0) = v(x_0) = u(Qx_0) = u(|x_0|e_1).$$

This implies the radial symmetry of u since  $x_0$  was arbitrary.

6. Prove that there is a unique solution  $u \in C^2(B(0,1)) \cap C(\overline{B}(0,1))$  to the boundary value problem

$$\begin{cases} \Delta u = u^3 & \text{in } B(0,1), \\ u = 0 & \text{on } \partial B(0,1). \end{cases}$$

*Proof.* Clearly v = 0 is a solution. We need to show that it is unique. Suppose on the contrary that there exists a solution  $u \in C^2(B(0,1)) \cap C(\overline{B}(0,1))$  that does not vanish identically in B(0,1). We may assume that

$$E_{+} := \{ x \in B(0,1) : u(x) > 0 \} \neq 0;$$

otherwise we consider -u. Let F be a connected component of  $E_+$ . Now we know that

$$-\Delta u = -u^3 < 0 \quad \text{in } F$$

 $\operatorname{and}$ 

$$u = 0$$
 on  $\partial F$ .

But then by conclusion (b) in problem 1, we have that

$$\max_{\overline{F}} u = \max_{\partial F} u = 0$$

This is a contradiction since u > 0 in F.