

$$\textbf{DATASTA MALLIKSI, kaavat}$$

$$S=\sqrt{S^2}=\sqrt{\frac{1}{n-1}\sum_{i=1}^n(X_i-\bar X)^2}$$

$$\mathrm{Var}(\bar X) = \frac{\sigma^2}{n}$$

$$\mathrm{SE}(\bar{x}) = \frac{s}{\sqrt{n}}$$

$$\frac{T_n - \mathrm{E}(T)}{\sqrt{\mathrm{Var}(T_n)}} \stackrel{D}{\rightarrow} Z \sim N(0,\,1)$$

$$b(T)=\mathrm{E}(T)-\theta$$

$$P(a\leq \theta \leq b)=1-\alpha$$

$$t=\frac{Y}{\sqrt{\frac{1}{n}\sum_{i=1}^nZ_i^2}}\sim t(n)$$

$$P(|\bar{x}-\mu|\leq d)=1-\alpha$$

$$P\left(\bar{x}-t_{\alpha/2,\,n-1}\frac{s}{\sqrt{n}}\leq\mu\leq\bar{x}+t_{\alpha/2,\,n-1}\frac{s}{\sqrt{n}}\right)=1-\alpha$$

$$t=\frac{\bar{X}_A-\bar{X}_B}{S\sqrt{\frac{1}{n_A}+\frac{1}{n_B}}}\sim t(n_A+n_B-2)$$

$$S^2=\frac{(n_A-1)S_A^2+(n_B-1)S_B^2}{n_A+n_B-2}$$

$$t=\frac{\bar{X}_A-\bar{X}_B}{\sqrt{\frac{S_A^2}{n_A}+\frac{S_B^2}{n_B}}}\sim t(df)$$

$$\frac{1}{df}=\frac{c^2}{n_A-1}+\frac{(1-c)^2}{n_B-1},\,\,c=\frac{\frac{S_A^2}{n_A}}{\frac{S_A^2}{n_A}+\frac{S_B^2}{n_B}}$$

$$\bar{X}_A-\bar{X}_B\pm t_{\alpha/2,\,df}\mathrm{SE}(\bar{X}_A-\bar{X}_B)$$

$$t=\frac{\bar{d}}{S_d/\sqrt{n}}\sim t(n-1)$$

$$t=\frac{\bar{X}-\mu_0}{S/\sqrt{n}}\sim t(n-1)$$

$$Z=\frac{p_A-p_B}{\sqrt{p(1-p)(\frac{1}{n_A}+\frac{1}{n_B})}} \rightarrow W \sim N(0,\,1)$$

$$p = \frac{n_A p_A + n_B p_B}{n_A + n_B}$$

$$Z=\frac{p-\theta_0}{\sqrt{\theta_0(1-\theta_0)/n}}\sim N(0,\,1),$$

$$\text{kun } \min\{n\theta_0,\, n(1-\theta_0)\}\geq 10$$

$$\mathrm{SE}(p) = \sqrt{\frac{p(1-p)}{n}}$$

$$p \pm z_{\alpha/2} \mathrm{SE}(p)$$

$$\mathrm{SE}(p_A - p_B) = \sqrt{\frac{p_A(1-p_A)}{n_A} + \frac{p_B(1-p_B)}{n_B}}$$

$$(p_A - p_B) \pm z_{\alpha/2} \mathrm{SE}(p_A - p_B)$$

$$e_{ij}=\frac{f_{i\cdot}f_{\cdot j}}{n},\;z_{ij}=\frac{f_{ij}-e_{ij}}{\sqrt{e_{ij}}}$$

$$\chi^2 = \sum_{i=1}^r \sum_{j=1}^c \frac{(f_{ij} - e_{ij})^2}{e_{ij}} \sim \chi^2((r-1)(c-1))$$

$$r = \frac{\frac{1}{n-1}\sum_{i=1}^n(x_i-\bar{x})(y_i-\bar{y})}{s_xs_y}$$

$$T=\frac{r\sqrt{n-2}}{\sqrt{1-r^2}}\sim t(n-2)$$

$$r_c=\frac{t_{\alpha/2,\,n-2}}{\sqrt{n-2+t_{\alpha/2,\,n-2}^2}}$$

$$P \approx 2\left[1-\Phi\left(\frac{|s-\frac{n}{2}|}{\sqrt{n}/2}\right)\right]$$

$$U=n_An_B+\frac{n_A(n_A+1)}{2}-R_A$$

$$Z=\frac{U-\frac{n_An_B}{2}}{\sqrt{\frac{n_An_B(n_A+n_B+1)}{12}}} \rightarrow W \sim N(0,\,1)$$

$$H=\frac{12}{N(N+1)}\sum_{i=1}^I\frac{R_i^2}{n_i}-3(N+1)~\sim\chi^2(I-1)$$

$$2\\$$

$$Y = a + bX + \epsilon$$

$$SS_E=\sum_{i=1}^n\epsilon_i^2=\sum_{i=1}^n[y_i-(a+bx_i)]^2$$

$$b=\frac{\sum_{i=1}^n(x_i-\bar{x})y_i}{\sum_{i=1}^n(x_i-\bar{x})^2},\;b=\frac{s_{xy}}{s_x^2}=r\frac{s_y}{s_x}$$

$$a=\bar{y}-b\bar{x}$$

$$\hat{\sigma}^2 = \frac{SS_E}{n-2}$$

$$\mathrm{Var}(b) = \frac{\sigma^2}{\sum_{i=1}^n(x_i-\bar{x})^2}$$

$$b\pm \text{SE}(b)t_{\alpha/2,\,df_E},\,\text{SE}(b)=\sqrt{\text{Var}(b)}$$

$$SS_T=SS_{REG}+SS_E,\, SS_T=\sum_{i=1}^n(y_i-\bar{y})^2$$

$$SS_{REG}=\sum_{i=1}^n(a+bx_i-\bar{y})^2$$

$$SS_E=\sum_{i=1}^n(y_i-a-bx_i)^2$$

$$df_T=n-1,\,\, df_{REG}=1,\,\, df_E=n-2$$

$$r^2=\frac{SS_{REG}}{SS_T}=1-\frac{SS_E}{SS_T}$$

$$F=\frac{SS_{REG}/df_{REG}}{SS_E/df_E}=\frac{SS_{REG}}{SS_E/df_E}\sim F(1,\,n-2)$$

$$T=\frac{b}{\text{SE}(b)}\sim t(n-2)$$

$$F_r=(n-2)\frac{r^2}{1-r^2}\sim F(1,\,n-2)$$

$$a+bx_0\,\pm\,t_{\alpha/2,\,df_E}\hat{\sigma}\sqrt{1+\frac{1}{n}+\frac{(x_0-\bar{x})^2}{\sum_{i=1}^n(x_i-\bar{x})^2}}$$

$$y_{ij} = \mu + \alpha_i + \epsilon_{ij}$$

$$SS_T=SS_{TR}+SS_E$$

$$3\\$$

$$SS_T = \sum_{i=1}^k\sum_{j=1}^n(y_{ij}-\bar{y})^2$$

$$SS_{TR}=n\sum_{i=1}^k(\bar{y}_i-\bar{y})^2$$

$$SS_E=\sum_{i=1}^k\sum_{j=1}^n(y_{ij}-\bar{y}_i)^2$$

$$df_T=N-1,\; df_{TR}=k-1,\; df_E=N-k$$

$$F=\frac{MS_{TR}}{MS_E}=\frac{SS_{TR}/df_{TR}}{SS_E/df_E}=$$

$$= \frac{N-k}{k-1}\cdot \frac{n\sum_{i=1}^k (\bar{y}_i-\bar{y})^2}{\sum_{i=1}^k\sum_{j=1}^n(y_{ij}-\bar{y}_i)^2} \sim F(df_{TR},\, df_E)$$

$$W=Q_{\alpha,\,k,\,df_E}\sqrt{MS_E/n},\; n=2/(1/n_i+1/n_j)$$

$$W=Q_{\alpha,\,k,\,\infty}\sqrt{\frac{n^2k(nk+1)}{12}}$$

$$P(B_i|A)=\frac{P(B_i)P(A|B_i)}{P(A)}=\frac{P(B_i)P(A|B_i)}{\sum_{j=1}^k P(B_j)P(A|B_j)}$$

$$p(\Theta|X)=\frac{p(\Theta)p(X|\Theta)}{p(X)}=\frac{p(\Theta)p(X|\Theta)}{\int_\Theta p(\Theta)p(X|\Theta)\;d\Theta}$$

$$\phantom{-}4$$